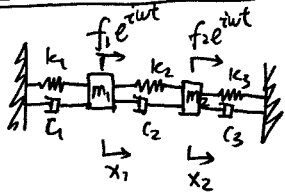


II. 2DOF

Complex number approach to 2DOF systems



$$\begin{pmatrix} m_1 & \\ & m_2 \end{pmatrix} \begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix} + \begin{pmatrix} c_1+c_2 & -c_2 \\ -c_2 & c_2+c_3 \end{pmatrix} \begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} + \begin{pmatrix} k_1+k_2 & -k_2 \\ -k_2 & k_2+k_3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} e^{i\omega t}$$

Note: Classical normal modes ~~exist~~ exist only when there is no damping.

Define: $[Z(s)] \equiv s^2 [m] + s [c] + [k]$

Suppose $\underline{x} = \underline{a} e^{i\omega t}$ ($\underline{a} \in \mathbb{C}^2$),

$$([m](i\omega)^2 + [c](i\omega) + [k]) \underline{a} = \underline{f}$$

$$\Rightarrow \underline{a} = [Z(i\omega)]^{-1} \underline{f}$$

For homogeneous solutions, let $\underline{x} = \underline{\lambda} e^{st}$,

$$([m]s^2 + [c]s + [k]) \underline{\lambda} = 0$$

$$\Rightarrow [Z(s)] \underline{\lambda} = 0$$

Let $\det[Z(s)] = 0$, we get $s = s_1, s_2, s_3$, or s_4 , with $\underline{\lambda} = \underline{\lambda}_1, \underline{\lambda}_2, \underline{\lambda}_3$, and $\underline{\lambda}_4$. (2)

The complete solution is:

~~$$\underline{x}(t) = \sum_{j=1}^4 \underline{\lambda}_j e^{s_j t} + [Z(i\omega)]^{-1} \underline{f} e^{i\omega t}$$~~

Define $r_j \equiv \frac{\lambda_{2j}}{\lambda_{1j}}$,

From $[Z(s_j)] \underline{\lambda}_j = 0$, we get $r_j = -\frac{z_{11}(s_j)}{z_{22}(s_j)}$ (3)

$\underline{x}(t)$ has the form :

$$\underline{x}(t) = \sum_{j=1}^4 \lambda_{1j} \begin{pmatrix} 1 \\ r_j \end{pmatrix} e^{s_j t} + \underline{a} e^{i\omega t} \quad (*)$$

With I.C.'s $\underline{x}(0) = \underline{x}_0$, $\dot{\underline{x}}(0) = \dot{\underline{x}}_0$, we have

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ r_1 & r_2 & r_3 & r_4 \\ s_1 & s_2 & s_3 & s_4 \\ r_1 s_1 & r_2 s_2 & r_3 s_3 & r_4 s_4 \end{pmatrix} \begin{pmatrix} \lambda_{11} \\ \lambda_{12} \\ \lambda_{13} \\ \lambda_{14} \end{pmatrix} = \begin{pmatrix} x_{01} - a_1 \\ x_{02} - a_2 \\ \dot{x}_{01} - i\omega a_1 \\ \dot{x}_{02} - i\omega a_2 \end{pmatrix} \quad (4)$$

Solving the equation gives λ_{1j} .

Hence, the complete solution is (*), with parameters determined by (1) ~ (4).

~~2/3~~