

Thm = (Minkowski's inequality)

A, B pos def, then

$$[\det(A+B)]^{\frac{1}{n}} \geq [\det(A)]^{\frac{1}{n}} + [\det(B)]^{\frac{1}{n}}$$

equally iff $B = cA$, some $c > 0$

Oct. 22 Linear programming

3 Possible cases:

- (1) feasible space empty
- (2) cost function unbounded in feasible space
- (3) ✓ cost function has min/max in feasible space.

Thm: Optimal solutions occurs at the "corners" of the hyper spaces.

Methods to find a solution:

(0) Compute corners, evaluate cost at corners.

$\binom{m+n}{n}$ possibilities.

(m additional constraints, n variables)

(1) ~~Dantzig's~~ Dantzig's simplex method

Phase I: find a corner

Phase II: move to new corner while ~~lowering~~ lowering cost.

(2) Karmarkar's method

starts inside, moves to the boundary.

Min/max duality principle.

General setup:

minimize CX

subject to $x \geq 0$ & $AX \geq b$

~~subject to~~
(n ineqs) (m ineqs)

maximize: CX

subject to: $x \geq 0$ and

$AX \leq b$

Dantzig's simplex method: $(AX \leq b)$

Def: "corner" is an intersection of n hypersurfaces that satisfies ~~satisfies all~~ all $m+n$ inequalities.

Note: There are at most $\binom{m+n}{n}$ "corners."

Def: "edge" is an intersection of $n-1$ hypersurfaces bounding the feasible set.

"slack variable" $w = AX - b$

$$\begin{bmatrix} A & I \end{bmatrix} \begin{bmatrix} x \\ w \end{bmatrix} = b \quad \begin{matrix} x \geq 0 \\ w \geq 0 \end{matrix}$$

$m \times n$ $m \times m$ $(m+n) \times 1$

new A · new x = \bar{b} ; new $x \geq 0$

Append 0's to cost function.

Phase I: Assume we have a corner in the feasible set, where n components of new x are 0.

Def: A solution is basic when ~~is a~~ n components of the new x are 0.

Def: A solution is feasible when new $x \geq 0$.

Def: A corner is degenerate if more than n components of x are 0.

Note: Degenerate corners are theoretically bad, but practically negligible.

Oct. 29

~~$x = [A^T A^T A^T]$~~ ~~$x = [A^T A^T A^T]$~~
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Linear programming is in P. (polynomial algorithm)

stats w/ rescaling algorithm.

Projection: $P = I - A^T (CA^T)^{-1} A$ ~~$CA^T x = y$~~

Algorithm: 1. Start anywhere, construct diagonal D from x^k , st.

$$D^{-1} x^k = e \quad (e = (1, 1, \dots, 1))$$

2. Compute projection $P D c$ $(AD^2 A^T y = AD^2 c)$
 $P D c = D c - D A^T y$

3. Find s st. $e - s P D c$ has zero component

4. Reduce s by a factor α (e.g. $\alpha = 0.96$)

5. New vector is $x^{k+1} = x^k - s P D c$.