

III

Maximum Likelihood Estimators (MLE)

$$X \sim f(x|\theta)$$

$$\text{Likelihood function } L(\theta|\underline{x}) \equiv \prod_{i=1}^n f(x_i|\theta)$$

Def: Maximum likelihood estimator (MLE) of the parameter θ based on a sample \underline{x} is $\hat{\theta}(\underline{x})$, where

$$L(\hat{\theta}(\underline{x})|\underline{x}) = \sup_{\theta} L(\theta|\underline{x}), \quad \forall \text{ sample point } \underline{x}.$$

Note: 1° The MLE is the parameter point for which the observed sample is most likely.

2° Inherent drawbacks of finding ^{the} maximum of a fn:

- 1) finding and verifying the global maximum
- 2) numerical sensitivity of the maximum.

Def: Induced likelihood function L^* for $\eta = \tau(\theta)$ is

$$L^*(\eta|\underline{x}) \equiv \sup_{\{\theta: \tau(\theta)=\eta\}} L(\theta|\underline{x})$$

The value $\hat{\eta}$ ^{that} maximizes $L^*(\eta|\underline{x})$ will be called the MLE of $\eta = \tau(\theta)$.

Thm: (Invariance property of MLEs)

If $\hat{\theta}$ is MLE of θ , then \forall fn. $\tau(\theta)$, the MLE of $\tau(\theta)$ is $\tau(\hat{\theta})$.

Proof: 1° The maxima of L and L^* coincide,

$$L^*(\hat{\eta}|\underline{x}) \equiv \sup_{\eta} \sup_{\{\theta: \tau(\theta)=\eta\}} L(\theta|\underline{x})$$

$$= \sup_{\theta} L(\theta|\underline{x})$$

$$= L(\hat{\theta}|\underline{x})$$

$$2^\circ L(\hat{\theta}|\underline{x}) = \sup_{\{\theta: \tau(\theta)=\tau(\hat{\theta})\}} L(\theta|\underline{x})$$

$$(\hat{\theta} \in \{\theta: \tau(\theta)=\tau(\hat{\theta})\} \in \Theta)$$

$$= L^*(\tau(\hat{\theta})|\underline{x})$$

$$\therefore L^*(\tau(\hat{\theta})|\underline{x}) = L^*(\hat{\eta}|\underline{x}) \quad \square$$

Note: 1° There's nothing in the proof that precludes θ from being a vector, so the invariance property of MLE also holds in the multivariate case.

- Properties: *asymptotically*
1. In most cases, MLEs are consistent
- 1° MLE's are efficient. (Asymptotic property)
In most cases,
- 2° MLE is always fn. of sufficient stat.

Techniques for finding ~~MLE's~~ MLE's:
verifying

- 1° ~~MLE's~~ differentiation
- 2° direct maximization (unique attainable global upper bound).
- 3° log likelihood
 $(U(\hat{\theta}) = \frac{\partial}{\partial \theta} \log p(x; \theta) = 0; \text{MLE solves the score fn.})$
- 4° successive maximizations
- 5° the EM algorithm

- Note: 1° Using second derivative condition to check for maximum likelihood requires negative definiteness of the Hessian matrix, which is formidable.
- 2° It is always important to analyse the likelihood fn. as much as possible, to find the number and nature of its local maxima, before using numeric maximization.

The EM Algorithm:

This is an algorithm suited to find MLE for missing data problems, by constructing a sequence that is guaranteed to converge to the MLE.

$\underline{Y} = (Y_1, \dots, Y_n)$ incomplete data $\sim g(\underline{y} | \theta)$

$\underline{X} = (X_1, \dots, X_m)$ augmented data.

$(\underline{Y}, \underline{X})$ complete data $\sim \bullet f(\underline{y}, \underline{x} | \theta)$