

Driven Oscillations

1. Sinusoidal Driving Forces

1.1. equation of motion:

$$m\ddot{x} + c\dot{x} + kx = F_0 \cos \omega t.$$

using another notation,

$$\ddot{x} + 2\gamma\dot{x} + \omega_0^2 x = A \cos \omega t$$

where $2\gamma = \frac{c}{m}$, $\omega_0^2 = \frac{k}{m}$, $A = \frac{F_0}{m}$.

the solution of the above equation consists of two parts, a complementary function $X_c(t)$ and a particular function $X_p(t)$.

1.2. now we solve $X_p(t)$ using complex numbers.

let $X_p(t) = \text{Re}(C e^{i\omega t})$ (where C is complex),

and write the driving term as $\text{Re}(F_0 e^{i\omega t})$

then

$$\text{Re}(-\omega^2 C e^{i\omega t}) + 2\gamma \text{Re}(i\omega C e^{i\omega t}) + \omega_0^2 \text{Re}(C e^{i\omega t}) = \text{Re}(F_0 e^{i\omega t})$$

$$(-\omega^2 + 2i\gamma\omega + \omega_0^2) C e^{i\omega t} = \frac{F_0}{m} e^{i\omega t}$$

implying $C = \frac{F_0/m}{-\omega^2 + 2i\gamma\omega + \omega_0^2}$

$$= \frac{F_0/m (\omega_0^2 - \omega^2 - 2i\gamma\omega)}{(\omega_0^2 - \omega^2)^2 + 4\gamma^2\omega^2}$$

$$= A e^{-i\phi}$$

where amplitude $A = \frac{F_0/m}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\gamma^2\omega^2}}$

phase $\phi = \tan^{-1} \frac{2\gamma\omega}{\omega_0^2 - \omega^2}$ ($\phi \in [0, \pi]$)

then the particular solution is

$$X_p(t) = \text{Re}(C e^{i\omega t}) = \text{Re}(A e^{i(\omega t - \phi)}) = A \cos(\omega t - \phi)$$

X_p is called Steady State Solution

1.3. Amplitude of Resonance

resonance frequency is

$$\omega_R = \sqrt{\omega_0^2 - 2\gamma^2}$$

the resonance frequency is lower than the damping ~~coefficient~~ ^{frequency}
the maximum amplitude.

$$A = \frac{F_0/m}{2r\sqrt{\omega_0^2 - r^2}}$$

is case of small ~~damping~~ damping

$$A \approx \frac{F_0}{2m\gamma\omega_0} = \frac{F_0}{c\omega_0} \quad (\text{if } \gamma \rightarrow 0, A \rightarrow +\infty)$$

1.4 quality factor

it's ~~common~~ customary to describe the degree of damping in an oscillating system in terms of the "quality factor".

$$Q \equiv \frac{\omega_R}{2r}$$

when γ increases, Q decreases.

when γ is small, or Q is very large, the shape of resonance curve approaches that for an undamped oscillator;

when γ is large, or Q is very small, the resonance can be completely destroyed.

if γ is large, or Q is very small, the resonance frequency ω_R ~~is~~ lowers, and the maximum amplitude is small, and δ , which shows the delay, gets larger.

1.5 ~~total~~ energy

the total mechanical energy is time dependent. (steady state solution)

$$E = K + V$$

$$= \frac{1}{2}m\dot{x}^2 + \frac{1}{2}kx^2$$

$$= \frac{1}{2}mA^2\omega^2 \sin^2(\omega t - \phi) + \frac{1}{2}kA^2 \cos^2(\omega t - \phi)$$

$$= \frac{1}{2}mA^2 [\omega^2 \sin^2(\omega t - \phi) + \omega_0^2 \cos^2(\omega t - \phi)]$$

$$= \frac{1}{2}mA^2\omega_0^2 + \frac{1}{2}mA^2(\omega^2 - \omega_0^2) \sin^2(\omega t - \phi)$$

when ω is close to ω_0 , the ~~additional~~ additional component is small, then the total energy stays ~~at~~ at a level and oscillates with a small amplitude, and the ~~period~~ period is $\frac{\pi}{\omega}$, half of that of the driven oscillation.

main frequency?

No

Date

1.6* kinetic energy resonance.

$$K = \frac{1}{2} m \omega^2 A^2 \sin^2(\omega t - \phi)$$

the average kinetic energy over a period is

$$\bar{K} = \frac{1}{4} m \omega^2 A^2$$

let $\frac{d\bar{K}}{d\omega} = 0$, then

$$\omega_E = \omega_0$$

that is to say, the kinetic energy resonance occurs at the natural frequency of the system of undamped oscillations.

1.7 fourier series.

a periodic function can always be written as a series of many sinusoidal functions.

$$f(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} [A_n \cos(n\omega t) + b_n \sin(n\omega t)]$$

where $\omega = \frac{2\pi}{T}$, and T is the period.

where the coefficients a_n and b_n are determined by the follows.

$$A_n = \frac{\omega}{\pi} \int_{-\pi/\omega}^{\pi/\omega} f(t) \cos(n\omega t) dt, \text{ for } n=0,1,2, \dots$$

$$b_n = \frac{\omega}{\pi} \int_{-\pi/\omega}^{\pi/\omega} f(t) \sin(n\omega t) dt, \text{ for } n=1,2,3, \dots$$