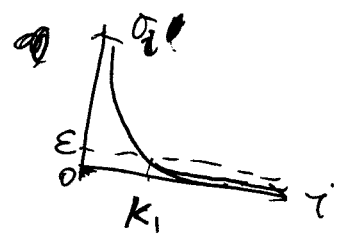


Project: Application of SVD to signal processing.

1. Matrix theory \leftrightarrow Image processing.
- | | |
|--|-----------------------------------|
| $A_{m \times n}$ | image grayscale image. |
| $A_{i,j}$ | pixel |
| $0 \sim 255$ | black ~ white |
| $R_{m \times n}, G_{m \times n}, B_{m \times n}$ | @ color image (RGB). |

8 bits
 $2^8 = 256$

Assumption: In general, an actual image is far from full rank. (effective rank)



2. ~~M~~ $M = L + N$

\uparrow output \uparrow input \uparrow random matrix

Def: white Gaussian noise is a matrix, with each entry a realization of a Gaussian r.v., and the entries are mutually independent.

$\text{rank}(L) = k_1, \text{rank}(M) = k > k_1$

3. Denoise ~~M~~ \rightarrow PSNR \uparrow
- \uparrow
- recover $L = VEW^*$
- \uparrow
- Maximum likelihood estimation.
- \uparrow (Gauss-Markov) $\textcircled{1}$
- Nearest rank k approximation.

Given M , solve for L s.t. M occurs with max prob.

Nearest rank k , estimation:

$$M \in M_{m,n}, \text{rank}(M) = k,$$

Find $L \in M_{m,n}, \text{rank}(L) = k_1 < k$, s.t.

$$L = \arg \min_L \|M - L\|_2$$

Answer: $L = VEW^*$

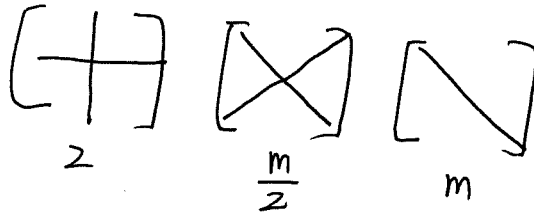
(2°)

with $M = V \Sigma(M) W^*$

$\left\{ \begin{array}{l} E \text{ takes the first } k_1 \text{ singular values of } \Sigma(M) \end{array} \right.$

Note: 1° Visual simplicity does not necessarily correspond to a low rank matrix.

E.g.



2° Practically useful methods may not be mathematically rigorous, but that's the way engineers do it.

Just like the simplex method is practically faster than some algorithms with polynomial complexity.

①

Proof: (Gaussian - Markov)

$$N_{ij} \sim N(0, \sigma^2)$$

$$M_{ij} - L_{ij} \sim N(0, \sigma^2)$$

random
variable

fixed

$$f(M_{ij} - L_{ij}) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(M_{ij} - L_{ij})^2}{2\sigma^2}}$$

Likelihood function; maximum likelihood estimation problem:

$$L = \arg \max_L \prod_{i=1}^m \prod_{j=1}^n f(M_{ij} - L_{ij})$$

$$= \arg \max_L \log \prod_{i=1}^m \prod_{j=1}^n f(M_{ij} - L_{ij})$$

$$= \arg \max_L \sum_{i=1}^m \sum_{j=1}^n \log f(M_{ij} - L_{ij})$$

$$= \arg \max_L \sum_{i=1}^m \sum_{j=1}^n \left[-\frac{1}{2\sigma^2} (M_{ij} - L_{ij})^2 + \log \frac{1}{\sqrt{2\pi\sigma^2}} \right]$$

$$= \arg \min_L \sum_{i=1}^m \sum_{j=1}^n (M_{ij} - L_{ij})^2$$

$$= \arg \min_L \|M - L\|_2$$

□

White Gaussian

2°

Proof: Recall: $A, B \in M_{m,n}$, then
 \forall unitarily invariant norm $\|\cdot\|$ on $M_{m,n}$,
 $\|A - B\| \geq \|\Sigma(A) - \Sigma(B)\|$

$$\begin{aligned} \therefore \|M - L\|_2 &\geq \|\Sigma(M) - \Sigma(L)\|_2 \\ &= g(\sigma_1(M) - \sigma_1(L), \dots, \sigma_k(M) - \sigma_k(L), \\ &\quad \sigma_{k+1}(M), \dots, \sigma_r(M), 0, \dots, 0) \\ &\geq g(0, \dots, 0, \sigma_k(M), \dots, \sigma_k(M), 0, \dots, 0) \\ &= \|M - VEW^*\| \end{aligned}$$

Take
 $\therefore L = VEW^*$

□

Frobenius norm
is unitarily ~~invariant~~
invariant.

$g(\cdot)$ symmetric
gauge fn

Symmetric fns are
monotone norms.

Thm = Gauss-Markov Theorem.

$$\vec{y} = X \vec{\theta} + \vec{\varepsilon}$$

~~X is $n \times n$, $\vec{\theta}$ is $n \times 1$, \vec{y} is $n \times 1$, $\vec{\varepsilon}$ is $n \times 1$~~

$$y^{(i)} = \vec{X}^{(i)T} \vec{\theta} + \varepsilon^{(i)}$$
$$= \vec{\theta}^T \cdot \vec{X}^{(i)} + \varepsilon^{(i)}$$
$$\begin{bmatrix} \vec{X}^{(1)T} \\ \vdots \\ \vec{X}^{(m)T} \end{bmatrix}$$

~~$\arg \max_{\vec{\theta}} L(\vec{\theta})$~~

$$L(\vec{\theta}) = p(\vec{y} | X, \vec{\theta}) = \prod_{i=1}^m p(y^{(i)} | \vec{X}^{(i)}, \vec{\theta})$$
$$= \prod_{i=1}^m \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{(y^{(i)} - \vec{\theta}^T \vec{X}^{(i)})^2}{2\sigma^2}\right\}$$

$$\arg \max \{L(\vec{\theta})\} \Leftrightarrow$$

$$\arg \max \{ \ln(L(\vec{\theta})) \} \Leftrightarrow \min \left\{ \sum_{i=1}^m (y^{(i)} - \vec{\theta}^T \vec{X}^{(i)})^2 \right\}$$

least square problem: $\vec{y} = X \vec{\theta}$

Probabilistic.

Deterministic.
